

§5. Intermittency

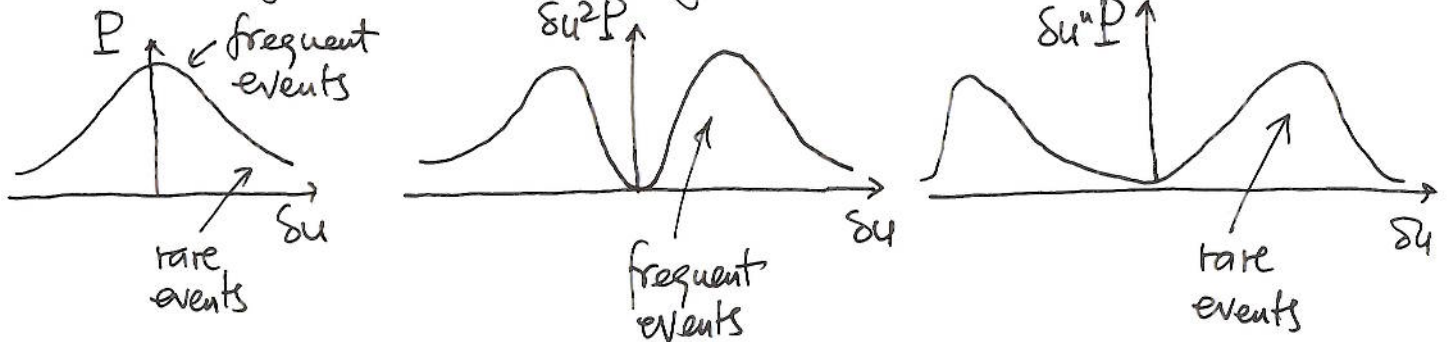
So far, we have an exact result for 3-d order statistics, $S_{III}(r) = -\frac{4}{3} \in \mathbb{R}$. (the $\frac{4}{3}$ law)

What about all other orders?

$$S_n(r) = \langle |\delta u \cdot \hat{r}|^n \rangle \sim r^{\zeta_n} \text{ for } l_v \ll r \ll L$$

• Can we find ζ_n ? (we know $\zeta_3 = 1$).

• Why do we care? High-order stats describe probabilities of rare events (large fluctuations) and come from the tails of the distribution function:



NB: These are hard to measure: it takes a long time for time averages and high resolution for volume averages
[rare in time] [sparse in space]

Note. It is not obvious that $S_n(r)$ exist - e.g. if $P(\delta u)$ was a power law, they would only exist up to some n . However, experiments suggest that (probably)

$$P(\delta u) \sim e^{-\delta u^\alpha}, \quad \alpha < 1 \quad \text{stretched exponential.}$$

• What does the K41 argument predict?

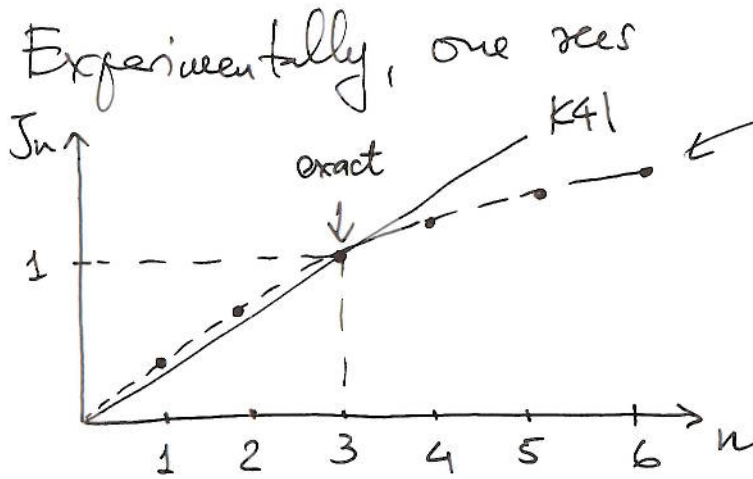
K41 assumes self-similarity in the inertial range:

$$\delta u_{\lambda \ell} = \lambda^h \delta u_{\ell} \Rightarrow S_n(\lambda \ell) = \lambda^{hn} S_n(\ell) \text{ for all } n.$$

Since $S_3(\ell) = -\frac{4}{5} \ell$ exactly, $h = \frac{1}{3}$ and we must have

$$\boxed{J_n = \frac{n}{3}} \text{ in K41}$$

• Experimentally, one sees



deviation from K41 grows with n .

Note: Mathematically, one can prove that

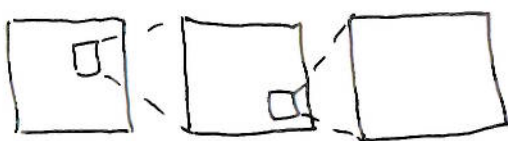
- 1) J_n vs. n is concave
- 2) J_n vs. n is non-decreasing

[see Frisch §8.4]

• So, something must be wrong with the assumption of self-similarity.

Self-similarity means that if we blow up small regions of the system, we see the same structure:

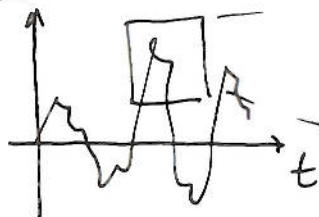
in space



$S_u(t)$

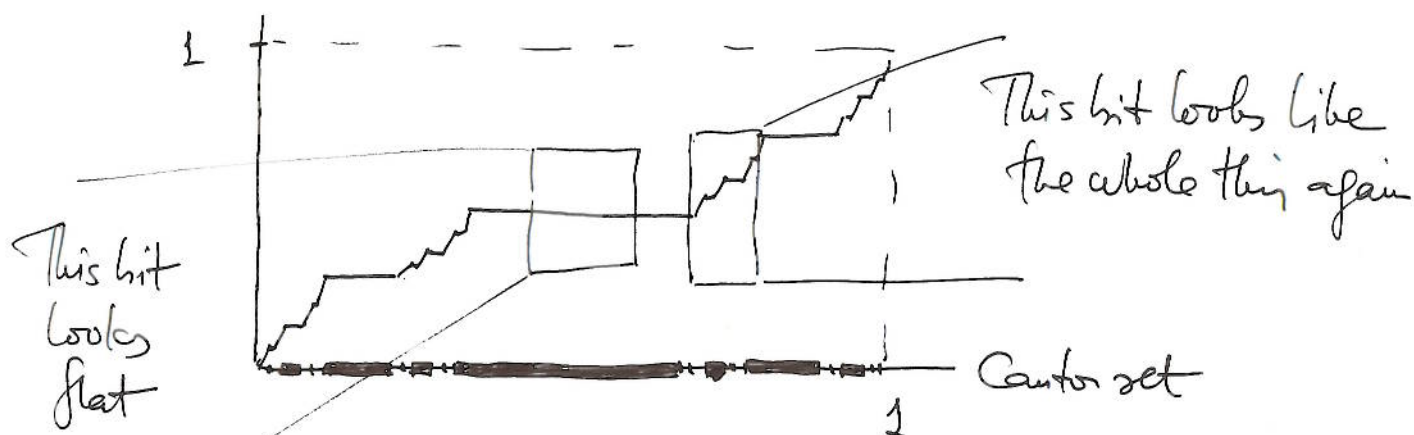
or time

$S_u(t)$



This is true, e.g., for a random walk.

But there are examples of fluctuating behaviour, for which this is not the case, e.g. Devil's staircase:



The smaller are the fragments we look at, the smaller is the probability that it won't just be flat!

Such non-self-similar behaviour is called intermittency

Intermittency is related to the volume (or time) - filling property of the field: crudely, let's imagine that the n th order structure function only comes from velocity differences concentrated in a fraction $\gamma_e^{(n)}$ of the system volume, where $\gamma_e^{(n)} \sim \left(\frac{l}{L}\right)^{\mu_{n/3}}$

Then

$$S_n(l) \sim \langle |\delta u_e|^n \rangle \sim \delta u_e^n \cdot \gamma_e^{(n)} \sim (\epsilon l)^{n/3} \left(\frac{l}{L}\right)^{\mu_{n/3}}$$

$$\sim \epsilon^{n/3} L^{-\mu_{n/3}} l^{\frac{n}{3} + \mu_{n/3}}$$

So
$$\boxed{\zeta_n = \frac{n}{3} + \mu_{n/3}}$$

NB: $\gamma_e^{(n)}$ must depend on n , otherwise $\mu_{n/3} = 0$ because $\zeta_3 = 1$

What is the physical origin of this lack of volume filling?

Obukhov & Kolmogorov (1962) proposed to consider

$$\epsilon_e(\vec{x}) = \frac{1}{\frac{4}{3}\pi l^3} \int_{|\vec{x}'-\vec{x}| < l} d^3x' \nu |\nabla \vec{u}|^2(\vec{x}')$$

average over a ball of radius l

Clearly, $\langle \epsilon_e(\vec{x}) \rangle = \epsilon$ Kolmogorov flux.

Batchelor & Townsend (1947): $\epsilon_e(\vec{x})$ is very intermittent (dissipation occurs in vortex filaments, in a small fraction of the volume)

Perhaps, at scale l , we have, generalizing K41:

$$S_{ll} \sim (\epsilon_e l)^{1/3}$$

Now $\langle \epsilon_e^m \rangle = \epsilon^m \left(\frac{l}{L}\right)^{\mu_m}$ and $\mu_1 = 0$, so $\langle \epsilon_e \rangle = \epsilon$

Then

$$S_n(l) \sim \langle \delta u_e^n \rangle \sim \langle (\epsilon_e l)^{n/3} \rangle = \langle \epsilon_e^{n/3} \rangle l^{n/3} = \epsilon^{n/3} L^{-\mu_{n/3}} l^{\frac{n}{3} + \mu_{n/3}}$$

so $S_3 \propto l$

So we have

$$\boxed{S_n = \frac{n}{3} + \mu_{n/3}}$$

where $\mu_{n/3}$ are scaling exponents of ϵ_e

This is called the refined similarity hypothesis.

Can we construct the statistics of ϵ_ℓ from some plausible physical assumption?

- Take a box the size of the system L .
The mean ~~dissipated power~~ dissipated power is
 $\langle \epsilon_L \rangle = \epsilon$

- Divide the box into smaller boxes of size dL , $d < 1$.
The mean dissipated power in each of these boxes is different (intermittency!)
Model this variation by writing

$$\epsilon_{dL} = \epsilon W_1$$

where W_1 is a random variable such that

$$W_1 \geq 0 \text{ and } \langle W_1 \rangle = 1 \text{ (so that } \langle \epsilon_{dL} \rangle = \epsilon)$$

- Bifide these boxes again: d^2L and let

$$\epsilon_{d^2L} = \epsilon_{dL} W_2 = \epsilon W_1 W_2,$$

where W_2 is independent of W_1 and distributed the same way, so $\langle \epsilon_{d^2L} \rangle = \epsilon$ again

- Iterate this procedure, so for boxes of size $\ell = d^k L$

$$\epsilon_\ell = \epsilon W_1 W_2 \dots W_k, \quad \langle \epsilon_\ell \rangle = \epsilon, \quad k = \log_d \frac{\ell}{L}$$

Then $\langle \epsilon_\ell^m \rangle = \epsilon^m \langle W^m \rangle^k = \epsilon^m d^{k \log_d \langle W^m \rangle} = \epsilon^m \left(\frac{\ell}{L} \right)^{\log_d \langle W^m \rangle}$

So we have $\langle \epsilon_e^m \rangle = \epsilon^m \left(\frac{L}{L}\right)^{\mu_m}$

where $\mu_m = \log_\alpha \langle W^m \rangle = \frac{\ln \langle W^m \rangle}{\ln \alpha}$

Note that for K41, $W=1$ (non random), $\mu_m=0$
 To model intermittency, we need to think about how W can be distributed.

- First of all, the way we divide our box must not influence the result, so replacing α by α^2 or α^r should not change the result. This means that the products $W_1 W_2 \dots$ or $W_1 \dots W_r$ must have the same distribution as W_1 .

If we let $w_i = \ln W_i$, this means that for arbitrary r ,

- $\sum_{i=1}^r w_i$ must have the same distribution as w_i ,
 so that $W_1 \dots W_r = e^{\sum_{i=1}^r w_i}$ has the same dist. as W_i .

- The lognormal model. An obvious candidate is a gaussian distribution:

$$P(w_i) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(w-\bar{w})^2}{2\sigma^2}} \quad \bar{w}, \sigma \text{ are parameters.}$$

Then $\sum_{i=1}^r w_i$ is also gaussian with mean = $r\bar{w}$,
 Variance = $r\sigma^2$

[NB: This is not an application of the Central Limit Theorem, which says that

$$\frac{1}{\sqrt{r}} \left[\sum_{i=1}^r w_i - r\bar{w} \right] \text{ is Gaussian as } r \rightarrow \infty \quad \forall w_i$$

but not necessarily $\sum_{i=1}^r w_i$!]

Thus, ϵ_e is lognormal (proposed by Osherson 1962)

$$\langle W^m \rangle = \langle e^{mw} \rangle = \int dw \frac{1}{\sqrt{2\pi\sigma^2}} e^{mw - \frac{(w-\bar{w})^2}{2\sigma^2}} = e^{m\bar{w} + \frac{\sigma^2 m^2}{2}}$$

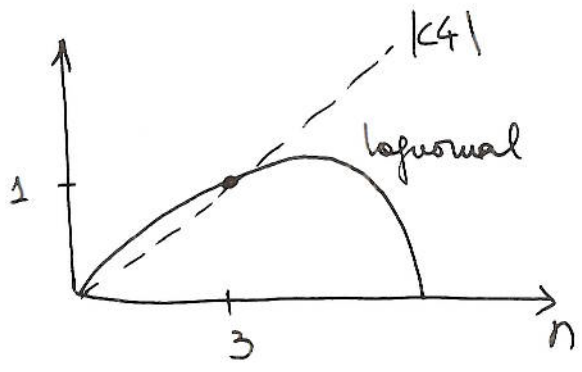
We must have $\langle W \rangle = 1 \Rightarrow \bar{w} + \frac{\sigma^2}{2} = 0$

This leaves only one parameter: \bar{w} and

$$\langle W^m \rangle = e^{\bar{w}m(1-m)} \Rightarrow \mu_m = \frac{\ln \langle W^m \rangle}{\ln m} = \left(\frac{\bar{w}}{\ln m} \right) m(1-m)$$

$$\boxed{\zeta_n = \frac{n}{3} + \mu_{n/3} = \frac{n}{3} + \frac{\mu}{18} n(3-n)}$$

$\frac{\mu}{2}$ free parameter.



This is no good because ζ_n must be monotonic (otherwise $\delta_{n/2}$ blows up as $l \rightarrow 0$ - see Frisch §8.4)

• The She-Lévy Model (1994)

Another possibility for an infinitely divisible distribution is Poisson:

$$\left. \begin{aligned} w &= q \ln \beta + w_0 \\ \text{or } W &= e^{w_0} \beta^q \end{aligned} \right\} \begin{array}{l} \beta \text{ and } w_0 \text{ parameters} \\ \text{and } q \text{ is a Poisson integer.} \end{array}$$

$$P(q) = \frac{\lambda^q}{q!} e^{-\lambda}, \quad \langle q \rangle = \lambda \leftarrow \text{another parameter.}$$

Thus, ϵ_e is log-Poisson (this interpretation of the SL Model was proposed by Dubnille 1994)

$$\begin{aligned} \langle W^m \rangle &= \sum_{q=0}^{\infty} e^{m(q \ln \beta + w_0)} \frac{\lambda^q}{q!} e^{-\lambda} = e^{mw_0 - \lambda} \sum_{q=0}^{\infty} \frac{(\lambda \beta^m)^q}{q!} = \\ &= e^{mw_0 - \lambda + \lambda \beta^m} = e^{mw_0 - \lambda(1 - \beta^m)} \end{aligned}$$

$$\langle W \rangle = 1 \Rightarrow w_0 - \lambda(1 - \beta) = 0 \Rightarrow \lambda = \frac{w_0}{1 - \beta}$$

so $\langle W^m \rangle = e^{w_0 \left(m - \frac{1 - \beta^m}{1 - \beta} \right)}$, whence

$$\mu_m = \frac{\ln \langle W^m \rangle}{\ln x} = \underbrace{\left(\frac{w_0}{\ln x} \right)}_{-x} \left(m - \frac{1 - \beta^m}{1 - \beta} \right) \left. \vphantom{\mu_m} \right\} \begin{array}{l} 2 \text{ parameters:} \\ x \text{ and } \beta \end{array}$$

$$\boxed{\bar{J}_n = \frac{n}{3} + \mu_{n/3} = (1-x) \frac{n}{3} + x \frac{1 - \beta^{n/3}}{1 - \beta}}$$

monotonic is $\beta < 1$

The challenge now is to find x and β .

We have $\langle \epsilon_e^m \rangle = \epsilon^m \left(\frac{l}{L} \right)^{-x(m - \frac{1-\beta^m}{1-\beta})}$

Consider $m \rightarrow \infty$:

$$\langle \epsilon_e^m \rangle \sim \epsilon^m \left(\frac{l}{L} \right)^{-xm + \frac{x}{1-\beta}} \quad (*)$$

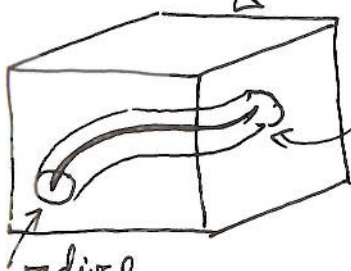
These large moments correspond to the most singular dissipative structures: \swarrow diss. power in these structures

$$\langle \epsilon_e^m \rangle \underset{m \rightarrow \infty}{\sim} [\epsilon_e^{(\infty)}]^m \phi_e \swarrow \begin{array}{l} \text{volume filling} \\ \text{fraction of these} \\ \text{structures} \end{array}$$

Here $\phi_e \sim \left(\frac{l}{L} \right)^{d-D}$, where $d (=3)$ is the dimension of space and D is the dimension of the most singular dissipative structures.

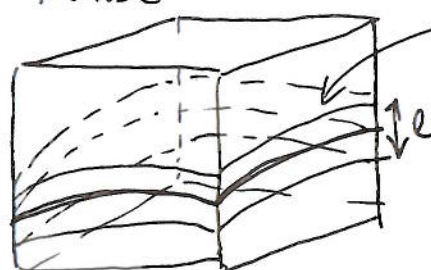
Indeed, ϕ_e is the probability for a ball of radius l to intersect with a diss. structure:

$D=1$
 $d=3$
filaments



volume $\Rightarrow \phi_e \sim \frac{l^2 L}{L^3} \sim \left(\frac{l}{L} \right)^2 = 3-1$

$D=2$
 $d=3$
sheets



volume $\Rightarrow \phi_e \sim \frac{l L^2}{L^3} \sim \left(\frac{l}{L} \right)^1 = 3-2$

Thus, $\langle \epsilon_l^m \rangle \sim [\epsilon_l^{(\infty)}]^m \left(\frac{l}{L}\right)^{d-D} \equiv C$ codimension of the structures

Compare this with (x), we get

$$\epsilon_l^{(\infty)} \sim \epsilon \left(\frac{l}{L}\right)^{-x} \quad \text{and} \quad \frac{x}{1-\beta} = C \quad \Rightarrow \quad \boxed{\beta = 1 - \frac{x}{C}}$$

$$\boxed{Z_n = (1-x) \frac{n}{3} + C \left[1 - \left(1 - \frac{x}{C}\right)^{\frac{n}{3}} \right]}$$

Now we need x , i.e. the scaling of the dissipated power in the most singular structures.

SL assumes that most of the energy is dissipated in them and that the cascade time has the dimensional K41 scaling:

$$\epsilon_l^{(\infty)} \sim \frac{U^2}{\tau_l} \sim U^2 \epsilon^{1/3} l^{-2/3} \sim U^2 \left[\frac{U^3}{L}\right]^{1/3} l^{-2/3} \sim \epsilon \left(\frac{l}{L}\right)^{-2/3}$$

whence $\boxed{x = \frac{2}{3}}$

Finally, empirically we know that the diss. structures are vortex filaments, so $\boxed{C=2}$ ($D=1$).

This gives $\boxed{Z_n = \frac{n}{9} + 2 \left[1 - \left(\frac{2}{3}\right)^{\frac{n}{3}} \right]}$

This fits the experimental/observational data rather well.

Extended Self-Similarity (Benzi et al. 1993)

When measurements (simulations) are done with only moderately large Re , it is rather hard to get good scalings. But there is a nifty trick:

plot $S_n(l)$ not vs. l but vs. $S_3(l)$.

Since $S_3(l) \sim l$, we should have

$$S_n(l) \sim l^{\zeta_n} \sim S_3(l)^{\zeta_n}$$

so
$$\boxed{\zeta_n = \frac{\partial \ln S_n(l)}{\partial \ln S_3(l)}}$$

It turns out that this formula is much more robust than $\zeta_n = \frac{\partial \ln S_n(l)}{\partial \ln l}$ ~~even~~ at moderate Re , i.e. the deviations from scaling arising from lack of asymptoticity are correlated for all n and cancel when "relative" scaling exponents are computed. There is, however, no theory of this.