

§ 2. Turbulent Mixing

A. Turbulent Diffusion

Consider the motion of a particle in a turbulent fluid. The particle's coordinate (distance from the initial point of release) satisfies

$$\frac{d}{dt} \vec{x}(t) = \vec{u}(t, \vec{x}(t)) = \overset{\leftarrow}{\vec{u}_L(t)} \quad \begin{array}{l} \text{Lagrangian} \\ \text{velocity} \end{array}$$

$\tau_{\text{turbulent velocity field}}$

Then $\frac{d}{dt} \langle x^2 \rangle = 2 \langle \vec{x} \cdot \vec{u}_L \rangle = 2 \langle \vec{u}_L(t) \cdot \int dt' \vec{u}_L(t') \rangle$

ensemble average over many particles

$$= 2 \int_0^t dt' \langle \vec{u}_L(t) \cdot \vec{u}_L(t') \rangle$$

Lagrangian time-correlation function of the velocity.

For $t \gg \tau_{\text{corr}}$, the integral is independent of time and

$$\int_0^\infty dt' \langle \vec{u}_L(t) \cdot \vec{u}_L(t') \rangle = D \sim U^2 \tau_{\text{corr}}$$

$$\frac{d}{dt} \langle x^2 \rangle = 2D \Rightarrow \langle x^2 \rangle = 2Dt \quad \text{diffusion}$$

Intuitively, $\tau_{\text{corr}} \sim \frac{L}{U}$ turnover of the largest eddy

$$\text{so } D \sim UL$$

(similar to molecular diffusion $D \sim V_{\text{th}} \cdot \lambda_{\text{diff}}$)

- 11 -

Consider a tracer field (dye concentration, temperature...)

$$\frac{\partial \Theta}{\partial t} + \vec{u} \cdot \nabla \Theta = \kappa \nabla^2 \Theta$$

↑ molecular diffusion.

If we ignore molecular diffusion and average this equation, we get

$$\frac{\partial \langle \Theta \rangle}{\partial t} = - \nabla \cdot \langle \vec{u} \Theta \rangle =$$

$$= \nabla \cdot \langle \vec{u}(t) \int_0^t dt' \vec{u}(t') \cdot \nabla \Theta(t') \rangle$$

Negligibly,

averages can be

split because $\Theta(t')$

can only depend on
 \vec{u} at times before t'

$$= \nabla \cdot \int_0^t dt' \underbrace{\langle \vec{u}(t) \vec{u}(t') \rangle}_{C_{ij}(t-t')} \cdot \nabla \langle \Theta(t') \rangle$$

$$C_{ij}(t-t')$$

correlation tensor,
only depends on $t-t'$
because of stationarity

$$= \nabla \cdot \int_0^t d\tau C_{ij}(\tau) \cdot \nabla \langle \Theta(t-\tau) \rangle \approx$$

$$C_{ij}(\tau) = \frac{1}{3} \delta_{ij} C(\tau)$$

(isotropy)

$$\langle \Theta(t) \rangle - \tau \frac{\partial}{\partial t} \langle \Theta(t) \rangle + \dots$$

small (to be checked)
as $t \gg \tau_{\text{corr}}$

$$\text{As } t \gg \tau_{\text{corr}}, \quad \int_0^t d\tau C(\tau) \rightarrow D = \text{const.}$$

So we have

(also space-independent
because of homogeneity)

$$\boxed{\frac{\partial \langle \Theta \rangle}{\partial t} = \frac{1}{3} D \nabla^2 \langle \Theta \rangle}$$

$$\text{NB: } \frac{\tau \frac{\partial \langle \Theta \rangle}{\partial t}}{\langle \Theta \rangle} \sim \frac{\tau_{\text{corr}} D}{L_0^2} \sim \frac{\frac{L_0}{U} \cdot U L}{L_0^2} \sim \frac{L^2}{L_0^2} \ll 1$$

Thus, all this works for the large-scale variation of the scalar field (\gg scale of turbulence).

B.2-Particle Dispersion.

Now consider two ~~fixed~~ particles.

If one particle tells us ~~about~~ how a spot of dye migrates in a turbulent fluid, two particles will tell us how it spreads.

Distance between particles : $l(t)$.

Now, roughly speaking,

$$\frac{d l(t)}{dt} \sim S u_{\text{eff}}(t) - \text{velocity difference between the particles.}$$

i) $(l < l_v) \Rightarrow S u_e \sim \left(\frac{\epsilon}{\nu}\right)^{1/2} l$, so

$$l(t) \sim l_0 e^{(\epsilon/\nu)^{1/2} t}$$

exponential separation (this is a highly nonrigorous demonstration, but one can show, for smooth random velocity fields that trajectories do separate exponentially)

2) $(l_v < l < L)$ \mapsto inertial range scales,
 $Su_e \sim (\epsilon l)^{1/3}$

$$\frac{dl}{dt} \sim (\epsilon l)^{1/3}$$

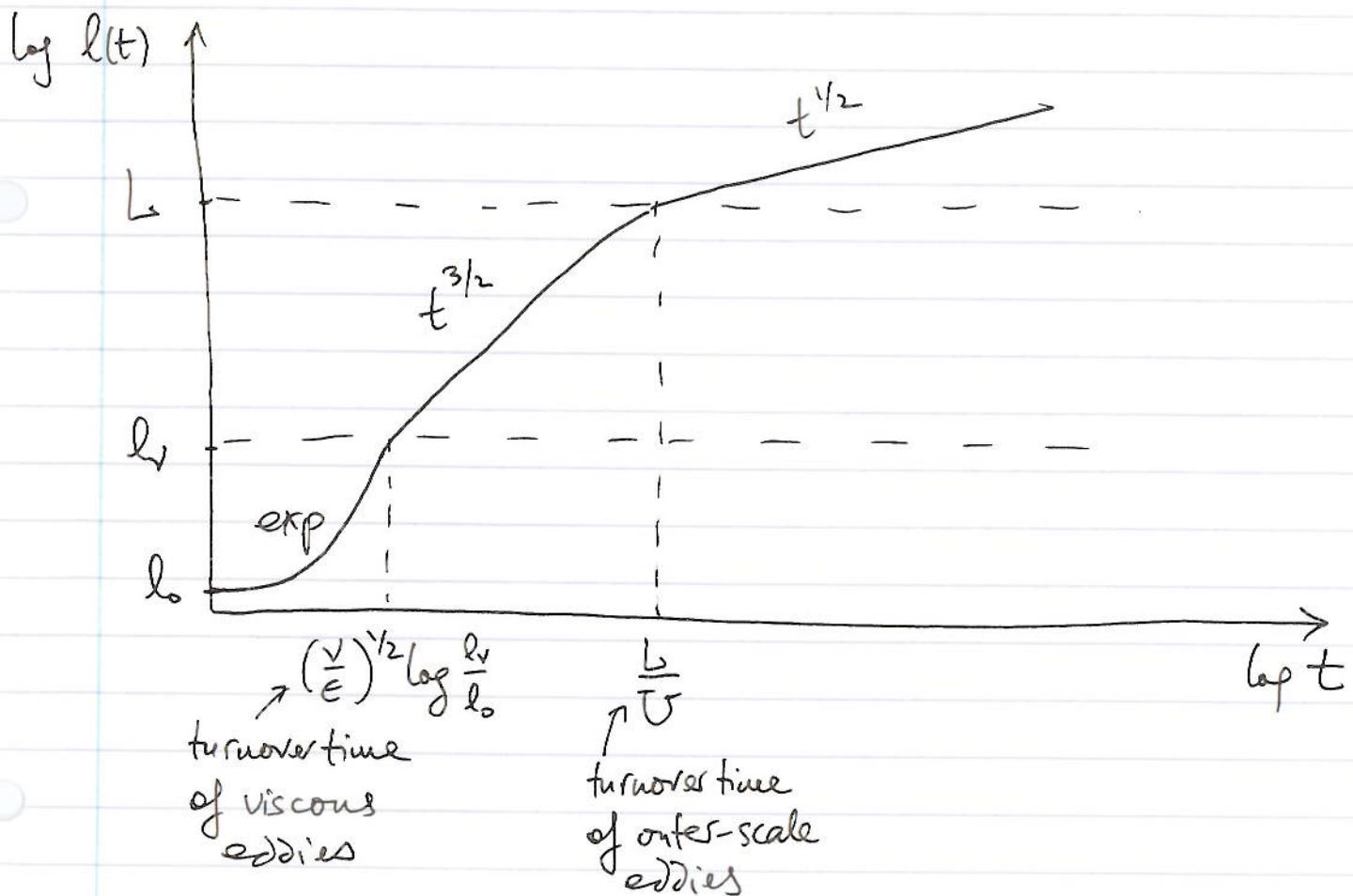
$$\frac{dl}{l^{4/3}} \sim \epsilon^{1/3} dt \mapsto l^{2/3} \sim \epsilon^{1/3} t$$

$$l(t) \sim \sqrt{\epsilon} t^{3/2}$$

- scalar separation / Richardson law

3) $(l > L)$ - this is just like turbulent diffusion,

so
$$l(t) \sim (Dt)^{1/2} \sim (ULt)^{1/2}$$



C. Spatial Structure of a Passive Scalar Field.

Let us go back to the advection-diffusion equation and ask what is the structure of the passive-scalar fluctuations.

$$\frac{\partial \theta}{\partial t} + \vec{u} \cdot \nabla \theta = \kappa \nabla^2 \theta + S$$

I have now added a source term, which I will assume to supply the scalar in a statistically stationary fashion on a typical spatial scale L_0 .

~~Passive scalar~~ We now construct a theory of "scalar turbulence" similar in spirit to K41.

Conservation of scalar variance:

$$\frac{\partial}{\partial t} \frac{\langle \theta^2 \rangle}{2} = \underbrace{\langle \theta S \rangle}_{\text{flux of variance into the system}} - \kappa \langle (\nabla \theta)^2 \rangle = 0$$

again, this
is a large
scale
quantity,
indep. of κ

$\left[\begin{matrix} \text{flux of variance} \\ \text{into the system} \end{matrix} \right]_{\theta}$

\uparrow
real
dissipation
of ~~variance~~
due to molecular
diffusivity

\uparrow
stationary
state

So by the same argument as for turbulence, the scalar field must develop small scales in order to dissipate.

NB: Turbulent diffusion is not real diffusion, it is simply the transfer of variance from large scales ($\gg L$) to small ones ($\lesssim L$).

At what scale does the molecular diffusion become important?

$$\frac{\bar{u} \cdot \nabla \theta}{\kappa \nabla^2 \theta} \sim \frac{(\kappa u_e/l) \nabla \theta_e}{\kappa \theta_e / l^2} \sim \frac{\kappa u_e l}{\kappa} \sim \frac{\epsilon^{1/3} l^{4/3}}{\kappa} \sim 1$$

"turbulent diffusion" at scale l

$l_x \sim \left(\frac{\kappa^3}{\epsilon}\right)^{1/4} \sim \left(\frac{\kappa}{\nu}\right)^{3/4} l_v$ diffusive scale

visc.-scale

We may assume that scale fluctuations of size l are dominantly affected by ~~veloci~~ motions of scale l (locality again, for similar reasons)

Let $Sc = \frac{\nu}{\kappa}$ Schmidt number

$$so \quad l_x \sim Sc^{-3/4} l_v$$

Note that we used the inertial range scaling for velocity, so this is all valid only if $l_x \gg l_v$, i.e. $Sc \ll 1$ (will discuss the opposite limit shortly).

Note: If L_0 is the scale of the source, we have

$$l_x \sim \frac{\kappa^{3/4}}{\epsilon^{1/4}} = \frac{\kappa^{3/4}}{\left(\frac{\kappa u_{L_0}^3}{L_0}\right)^{1/4}} = \left(\frac{\kappa}{\kappa u_{L_0} L_0}\right)^{3/4} L_0 = Pe^{-3/4} L_0$$

where $Pe = \frac{\kappa u_{L_0} L_0}{\nu}$ Peclet number
(analog of Re)

So, what is the scaling of $\delta\theta_e$ for $l_0 \gg l \gg l_\epsilon$?
 (This is called inertial-conductive range)

Like in K41, we assume locality, isotropy, homogeneity...

Then the flux of scalar variance is

$$\epsilon_\theta \sim \frac{\delta\theta_e^2}{T_e} \sim \text{const}$$

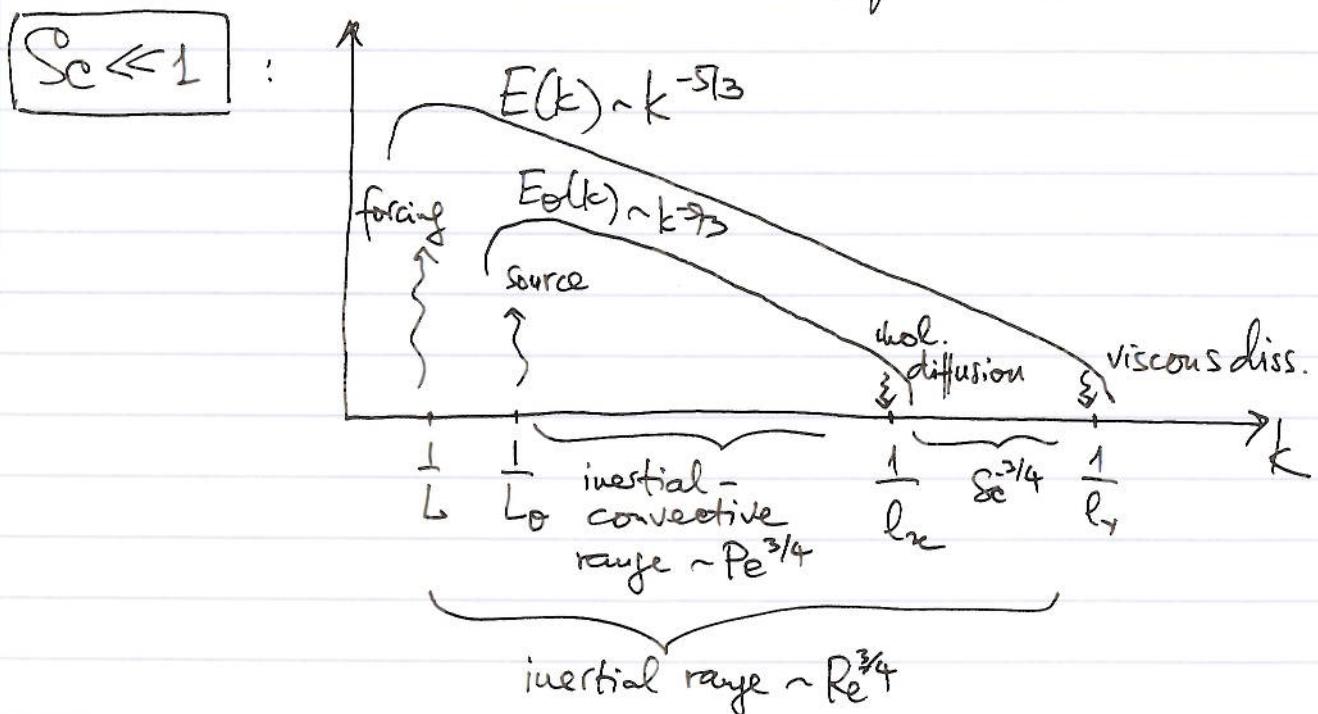
cascade time the same as for turbulence:

$$\frac{\delta u_e^2}{T_e} \sim \epsilon \Rightarrow T_e \sim \frac{\delta u_e^2}{\epsilon}, \text{ so we get}$$

$$\boxed{\delta\theta_e \sim \left(\frac{\epsilon_\theta}{\epsilon}\right)^{1/2} \delta u_e \sim \frac{\epsilon^{1/2}}{\epsilon^{1/6}} l^{1/3}}$$

So the scalar traces the turbulence spectrum,

$$E_\theta(k) \sim \frac{\epsilon_\theta}{\epsilon^{1/3}} k^{-5/3} \quad \begin{matrix} \text{Obukhov-Corrsin} \\ \text{Spectrum} \end{matrix}$$



Now let us consider the case $\text{Sc} \gg 1$.

Then $x \ll \sqrt{\epsilon}$ and we expect that $l_x \ll l_y$.

To find it, again compare advective and diffusive terms, but this time use the viscous scaling for the velocity field:

$$\frac{\bar{u} \cdot \nabla \Theta}{x \nabla^2 \Theta} \sim \frac{(\delta \theta_e / \epsilon) \delta \theta_e}{x \delta \theta_e / l^2} \sim \frac{\delta \theta_e l}{x} \sim \frac{(\epsilon / \nu)^{1/2} l^2}{x} \sim 1$$

for $l \sim l_x$

$$l_x \sim x^{1/2} \left(\frac{\nu}{\epsilon} \right)^{1/4} \sim \left(\frac{x}{\nu} \right)^{1/2} \frac{\nu^{3/4}}{\epsilon^{1/4}} \sim \text{Sc}^{-1/2} l_y \ll 1$$

for $\text{Sc} \gg 1$

We have a new range of scales: $l_y \gg l \gg l_x$
 (called viscous-conductive range).

The usual constant-flux argument gives

$$\epsilon_0 \sim \frac{\delta \theta_e^2}{T_e} \sim \frac{\delta \theta_e^2}{(\nu/\epsilon)^{1/2}} \sim \text{const}$$

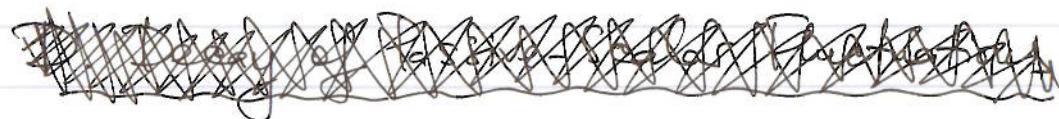
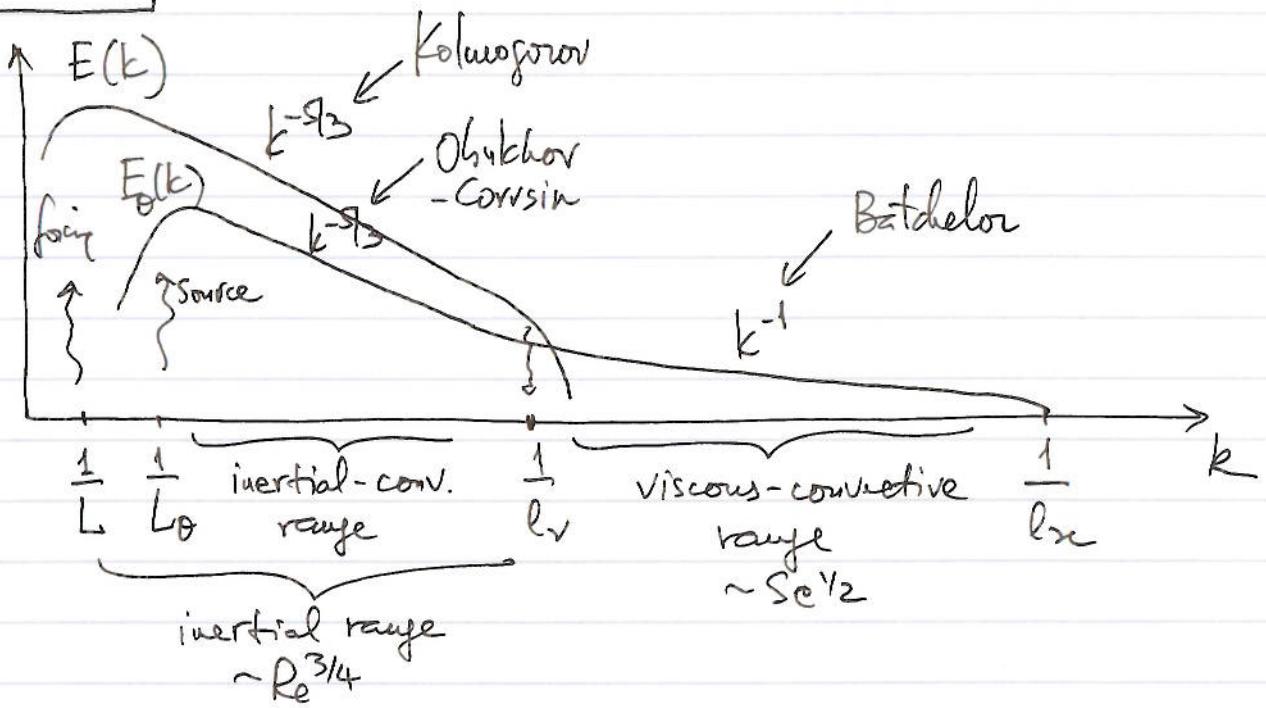
\swarrow the viscous eddy time

$$\delta \theta_e \sim \boxed{\epsilon_0^{1/2} \left(\frac{\nu}{\epsilon} \right)^{1/4}} \sim \text{const}$$

implying $E_0(k) \sim \boxed{\epsilon_0} \epsilon_0 \left(\frac{\nu}{\epsilon} \right)^{1/2} k^{-1}$ Batchelor Spectrum

Note that in order for this argument to work, we have to assume constant flux. Locality does not really work here because scalar fluctuations in the viscous-conductive range are all interacting with the velocity field at the viscous scale (a "large" scale from their point of view).

$\text{Sc} > 1$



Note. Batchelor theory also describes the situation in flows that are chaotic/random, but not turbulent, i.e. there is no inertial range ($Re \sim 1$). Again, there is only one characteristic time scale $\sim L/U$, which is the mix-up time for the scalar fluctuations, which should develop a k^{-1} spectrum.
 (Same story in 2D turbulence, where the energy cascade is inverse at the force-scale motions dominate, as far as mixing is concerned)

D. Decay of Scalar Fluctuations.

Let us now consider a situation where there is no source and we want to know how quickly the scalar variance will decay

$$\langle \delta \theta^2 \rangle \rightarrow 0$$

Until quite recently, it was believed that the answer to this question is local in the sense that it is controlled by the small-scale local properties of the flow. The argument went roughly as follows.

For any initial ~~chaotic~~ distribution of the scalar, small-scale structures quickly form and then are dissipated by diffusion.

The mixing rate must surely be determined by the fastest timescale of the flow, so, in the core of turbulence, by the turnover rate of the viscous eddies

$$\gamma \sim \left(\frac{\epsilon}{\nu}\right)^{1/2} \sim \frac{U}{L} Re^{1/2}$$

or in the case of a single-scale chaotic/random flow, by the stretching/shearing rate associated with it, so

$$\gamma \sim \frac{U}{L}$$

In either case, trajectories separate exponentially, so one expects something like $\langle \delta \theta^2 \rangle \sim \langle \delta \theta_0^2 \rangle e^{-2\gamma t}$ up to ~~and~~ some constant of order unity.

This is called Lagrangian stretching theories.

They can be made quite mathematical

— I will not go into details.

Two standard references are

Antonova et al. Phys. Fluids 8, 3094 (1996)

Balkovsky & Fouxon Phys. Rev. E 60, 4164 (1999)

[review: Falkovich et al. Rev. Mod. Phys. 73, 913 (2001)]

However, experimental and numerical evidence emerged that suggested that in fact the decay is much slower than predicted by these theories and seems to be controlled by the size of the system — even though the scalar structure is very small-scale.

This was called the strange mode (by Pierehumbert).

It is, in fact, not strange at all.

Consider what happens with a scalar field

in a box such that $L_{\text{box}} \gg L_{\text{flow}}$.

The large-scale ($L_{\text{box}} \gg l \gg L_{\text{flow}}$) component will be decaying by turbulent diffusion.

The slowest of all modes (Fourier modes, say) is the one with the smallest wave number:

$$\partial_t \Theta_{k_{\text{box}}} = -\frac{1}{3} D k_{\text{box}}^2 \Theta_{k_{\text{box}}} \quad k_{\text{box}} \sim L_{\text{box}}^{-1}$$

All others decay faster. ~~and possibly~~

The modes at scales comparable to or smaller than L_{flow} decay even faster ($\sim \frac{\delta u_e}{k}$) .

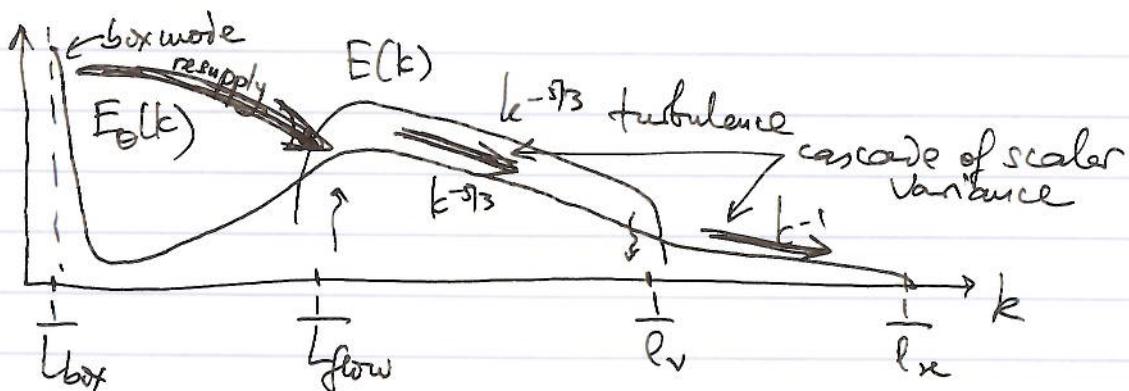
However, the slowly-decaying mode that is sitting at the box scale, will resupply scalar variance to smaller scales — that is, ~~misforn~~ indeed what turbulent diffusion is!

It is similar to having a scalar field with a very slowly decaying mean:

$$\Theta = \langle \Theta \rangle + \delta \Theta, \text{ so}$$

$$\partial_t \delta \Theta + \vec{u} \cdot \nabla \delta \Theta = \kappa \nabla^2 \delta \Theta - \underbrace{\vec{u} \cdot \nabla \langle \Theta \rangle}_{\text{just like a source term.}}$$

So the scalar field at $k \leq L_{\text{flow}}$ is similar to the case with a source:



References : Fereday & Haynes, Phys Fluids 16, 4359 (2004)
 Schekochihin, Haynes & Cowley
 Phys. Rev. E 70, 046304 (2004)

Haynes & Vanneste, Phys Fluids 17, 097103 (2005)