





Kinetic treatment of ions at the tokamak plasma-wall boundary

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Motivation

- Boundary conditions needed for fluid codes used to simulate the SOL plasma
- Ones currently used [1] are obtained using fluid equations: <u>aim</u> is to obtain boundary conditions using a kinetic treatment
- Could be used with drift kinetic/gyrokinetic codes of SOL
- Interesting problem from a purely theoretical point of view: <u>generalizing gyrokinetics to strongly distorted orbits in the</u> <u>magnetic presheath geometry</u>

[1] J. Loizu, P. Ricci, F.D. Halpern and S. Jolliet, *Phys. Plasmas* 19, 122307 (2012).

Geometry of divertor region



Boundary layers



[3] F. Militello and W. Fundamenski, Plasma Phys. Control. Fusion 53, 095002 (2011)

The magnetic presheath

- Focus on ion Larmor radius scale!
- Quasineutral $Zn_i(x) = n_e(x)$
- Use Boltzmann electrons

$$n_e(x) = n_\infty \exp\left(\frac{e\phi(x)}{T_e}\right)$$

- Ion orbits heavily distorted by the strong presheath electric field
- Ion density obtained with kinetic treatment



Ion trajectories with α =0

• Equations of mot $\dot{v}_x = -\frac{Ze}{m_i}\frac{d\varphi}{dz}$ $\dot{v}_y = -\Omega v_x$ $\dot{v}_z = 0$	tion: $\frac{b(x)}{dx} + \Omega v_y$	$y \xrightarrow{x} z$
Orbit position $\bar{\lambda}$ Perpendicular energy 2 Total energy 2	$\begin{aligned} \bar{c} &= x + (1/\Omega)v_y \\ U_\perp &= \frac{1}{2}v_x^2 + \\ \frac{1}{2}v_y^2 + \frac{Ze\phi}{m_i} \\ U &= U_\perp + \frac{1}{2}v_z^2 \end{aligned}$	$v_x = \pm V_x \left(\bar{x}, U_\perp, x \right) = \pm \sqrt{2 \left(U_\perp - \chi \left(x, \bar{x} \right) \right)}$ $v_y = \Omega \left(\bar{x} - x \right)$ $v_z = V_{\parallel} \left(U_\perp, U \right) = \sqrt{2 \left(U - U_\perp \right)}$
• Motion periodic if particle is trapped around a minimum of the effective potential $\chi(x,\bar{x}) = \frac{1}{2}\Omega^2 (x - \bar{x})^2 + \frac{Ze\phi(x)}{m_i}$		

 $x_{\rm M}$

 x_{b}

 x_{t}

Ion trajectories in system with $\alpha <<1$

- Orbit parameters \bar{x} and U_{\perp} slowly varying: $\dot{\bar{x}} \simeq -\alpha v_z$
- Total energy U conserved $\dot{U}_{\perp} \simeq -\alpha \Omega v_u v_z$
- Over small time intervals have ~ closed orbits (rings below)
- $\alpha \ll 1 \Rightarrow$ adiabatic invariant: $\mu(\bar{x}, U_{\perp}) = \frac{1}{\pi} \int_{x_{\perp}}^{x_{\perp}} \sqrt{2(U_{\perp} \chi(s, \bar{x}))} ds$
- Ion trajectories conserve μ and U to lowest order across magnetic presheath [4]



[4] R.H. Cohen and D.D. Ryutov, *Phys. Plasmas* 5, 808 (1998)

Closed orbit ion density

- Distribution function F constant when written in terms of μ and U
- If boundary condition at x→∞ is F(µ, U), closed ion orbits have distribution function F(µ, U) across the whole magnetic presheath!
- Ion density = integral in velocity of F, holding particle position x fixed
- To compute it, change velocity space variables $(v_{x'}, v_{y'}, v_z) \rightarrow (U_{\perp}, \bar{x}, U)$ [5]



Open orbit ion density

 Closed orbit density is not enough to solve for electrostatic
 potential in magnetic presheath

$$n_{i,\text{closed}}(0) = 0$$
$$\implies 0 = n_{\infty} \exp\left(\frac{e\phi_0}{T_e}\right)$$
$$\implies \phi_0 = -\infty$$

- Largeness of potential drop $\phi_0 < -->$ smallness of ion density at x=0
- Quantifying φ₀ requires keeping contribution to ion density at x=0 which comes from **open orbits**



- Calculated $n_{i,\text{open}}(x)$ which has size $\sqrt{\alpha} \leq n_{i,\text{open}}(x)/n_{\infty} \leq \alpha$
- With the open orbits included, recover known scaling for potential drop ϕ_0 across magnetic presheath $\frac{e\phi_0}{T_e} = \ln\left(\frac{n_{i,\text{open}}(0)}{n_{\infty}}\right) \sim \ln \alpha$

Conditions on distribution function

- Asymptotic analysis of boundary layers leads to solvability conditions at interface between different layers
- Define **sonic speed** $c_s = \sqrt{T_e/m_i}$
- We solve magnetic presheath numerically by using a distribution function that marginally satisfies Chodura condition at $x \rightarrow \infty$

$$\begin{split} f_{\infty}\left(\boldsymbol{v}\right) &\propto v_{z}^{2} \exp\left(-\frac{m_{i}}{2T_{i}}\left(v_{x}^{2}+v_{y}^{2}+v_{z}^{2}\right)\right) \text{ with } T_{i}=T_{e}\\ F\left(\mu,U\right) &\propto \left(U-\Omega\mu\right) \exp\left(-\frac{m_{i}U}{T_{i}}\right)\\ u_{\parallel\infty} &= 2\sqrt{\frac{2}{\pi}}c_{s} \simeq 1.60c_{s} \end{split}$$

• Should find Bohm condition satisfied at x=0

[6] K.-U. Riemann, J. Phys. D: Appl. Phys. 24, 493-518 (1991)
[7] E. R. Harrison and W. B. Thompson, Proc. Phys. Soc. 74, 145 (1959)

[8] A. Geraldini, F. I. Parra, F. Militello, in preparation





Numerical results: electrostatic potential



Distribution function at *x*=0



Conclusion

- Exploited conservation of total energy and adiabatic invariant to solve for ion distribution function in magnetic presheath
- For a given potential profile, found expressions for lowest order density of ions throughout magnetic presheath including open orbits that matter near *x*=0
- Developed a code that computes ion density and iterates over potential until quasineutrality is solved (with Boltzmann electrons)
- Derived kinetic form of Chodura's condition
- Numerical results consistent with kinetic Bohm condition at Debye sheath
- Ions entering the Debye sheath are "colder" at smaller angles



Future work:

- Solve the magnetic presheath numerically for different distribution functions and $T_{e}/T_{i}\,\text{ratios}$
- Study collisional layer to find correct boundary distribution function at magnetic presheath entrance