

# Small scales turbulence and LES modelling with GENE

*P. Morel, A. Banon Navarro, M. Albrecht-Marc and D. Carati*

*Université Libre de Bruxelles*

*F. Merz, T. Gorler and F. Jenko*

*Max Planck Institut für PlasmaPhysik - Garching*

# outline

Sub grid and modelling

Free energy balance

Hyperdiffusion as a first model

Dynamic procedure

Applying a filter to gyrokinetics equations solved in GENE leads to:

$$\partial_t \overline{\delta g} = \mathcal{Z} + \mathcal{L}[\overline{\delta g}] + \mathcal{N}[\overline{\delta g}, \overline{\delta g}] + \mathcal{T}[\delta g, \overline{\delta g}]$$

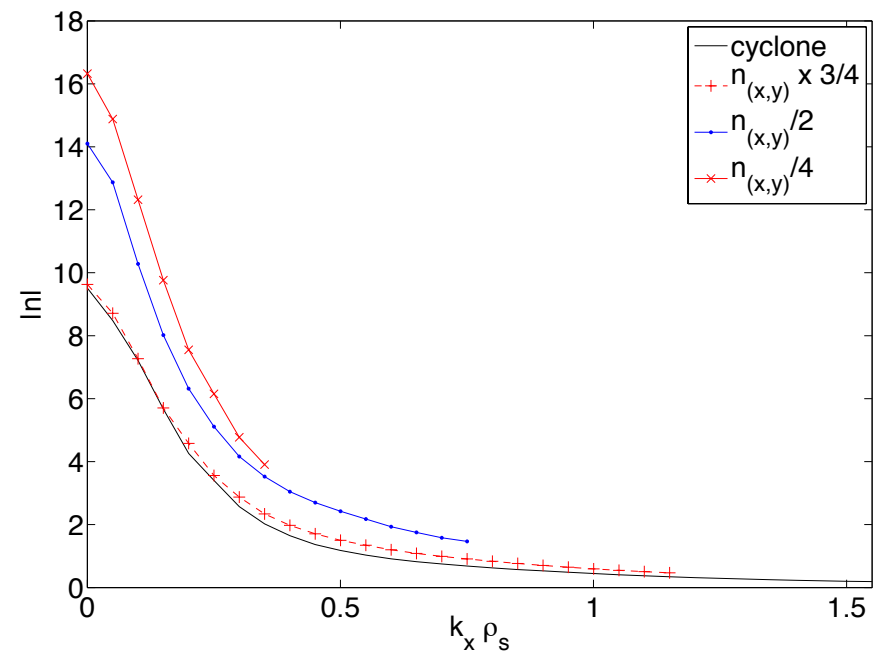
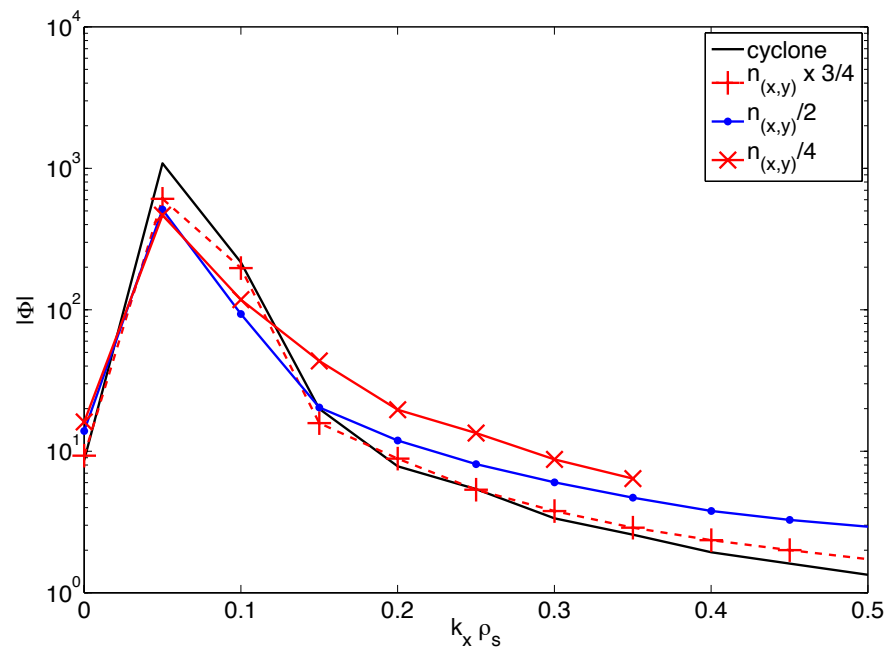
With the sub grid term:

$$\mathcal{T}[\delta g, \overline{\delta g}] = \overline{\mathcal{N}[\delta g, \delta g]} - \mathcal{N}[\overline{\delta g}, \overline{\delta g}]$$

To gain in resolution and numerical effort, this term has to be modelled and analysed.

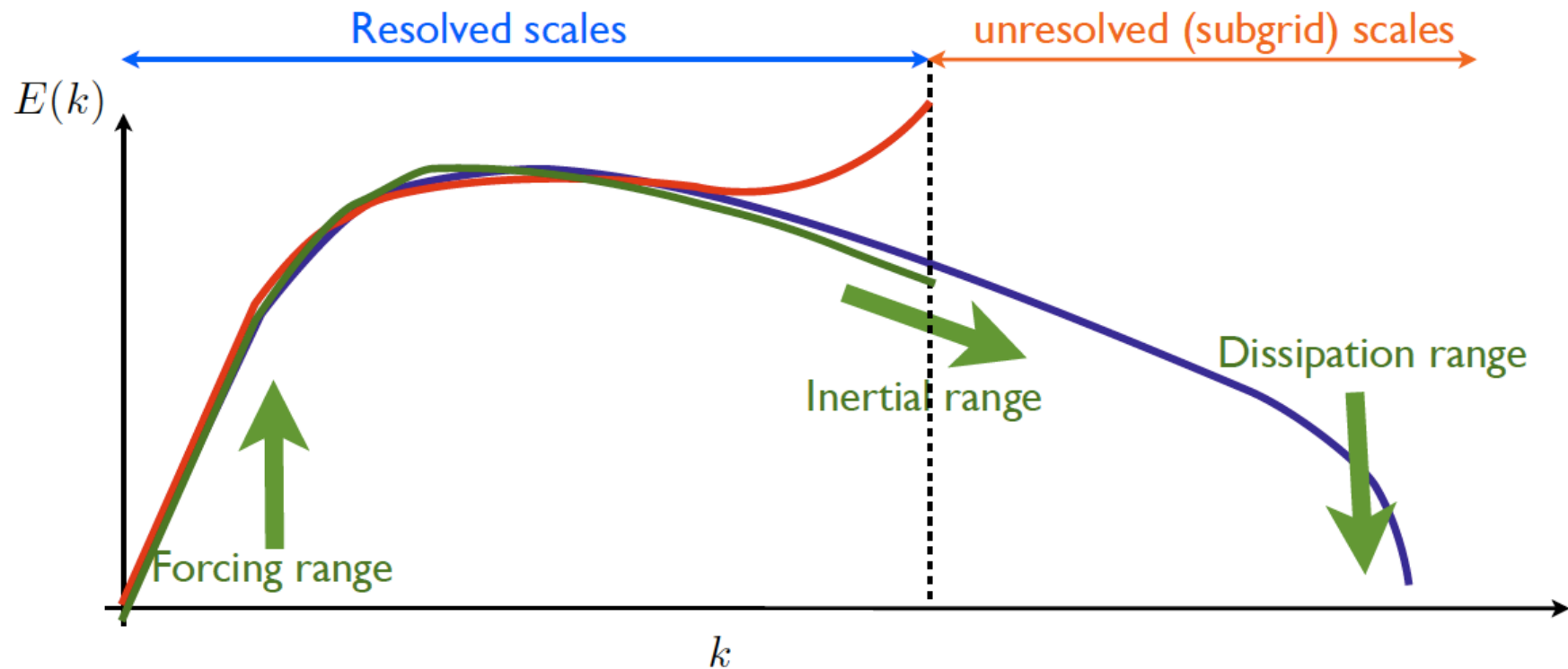
First analysis: under resolved study

Principle: decrease resolution without model, see what is lost:



*CBC case with decreasing perpendicular resolution  
electrostatic potential (left) and density (right) along  $k_x$  (radial): crucial need of a  
model!*

Basic idea: sub grid must insert some dissipations



A good candidate for quantifying these dissipation processes is the free energy

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## Free energy balance

In local version of GENE, free energy balance can be expressed:

$$\partial_t (\mathcal{F} + \mathcal{W}^\phi) = \mathcal{G}_0 + \mathcal{G} + \mathcal{H}_z + \mathcal{H}_{v_{\parallel}}$$

By applying the free energy operator:

$$\Omega. = \sum_s \sum_k \left\langle \int d\mu dv_{\parallel} \pi B_0 n_{0j} T_{0j} \left[ \frac{g_{-kj}}{F_{0j}} + \frac{q_j \chi_{-kj}}{T_{0j}} \right] \cdot \right\rangle$$

to Vlasov equation.

NB: the drive is a L.C of eq. gradients and fluxes

NBB: dissipation in collisionless regime ensured by hyper-diffusion operators

**Free energy balance – terms (adiabatic electrons)**

$$\partial_t (\mathcal{F} + \mathcal{W}^\phi) = \mathcal{G}_0 + \mathcal{G} + \mathcal{H}_z + \mathcal{H}_{v_{\parallel}}$$

$$\mathcal{F} = \sum_j \sum_k \left\langle \int d\mu dv_{\parallel} \pi B_0 n_{0j} T_{0j} \frac{|\delta f_{kj}|^2}{F_{0j}} \right\rangle$$

TdS: Entropy

$$\mathcal{W}^\phi = \frac{q_e^2 n_{e0}}{T_{e0}} \sum_k \left( \langle |\phi_k|^2 \rangle - |\langle \phi_k \rangle|^2 \right) + \sum_i \frac{q_{i0}^2 n_{i0}}{T_{i0}} \sum_k \langle [1 - \Gamma_0(b_{kj})] |\phi_k|^2 \rangle$$

Electrostatic

$$\mathcal{G} = \Omega. - \left[ \omega_{nj} + \left( v_{\parallel}^2 + \mu B_0 - \frac{3}{2} \right) \omega_{Tj} \right] F_{0j} i k_y \chi_{kj}$$

Gradients:  
Free energy  
sources

$$\mathcal{H}_z = \Omega. h_z \partial_z^4 f_{kj}$$

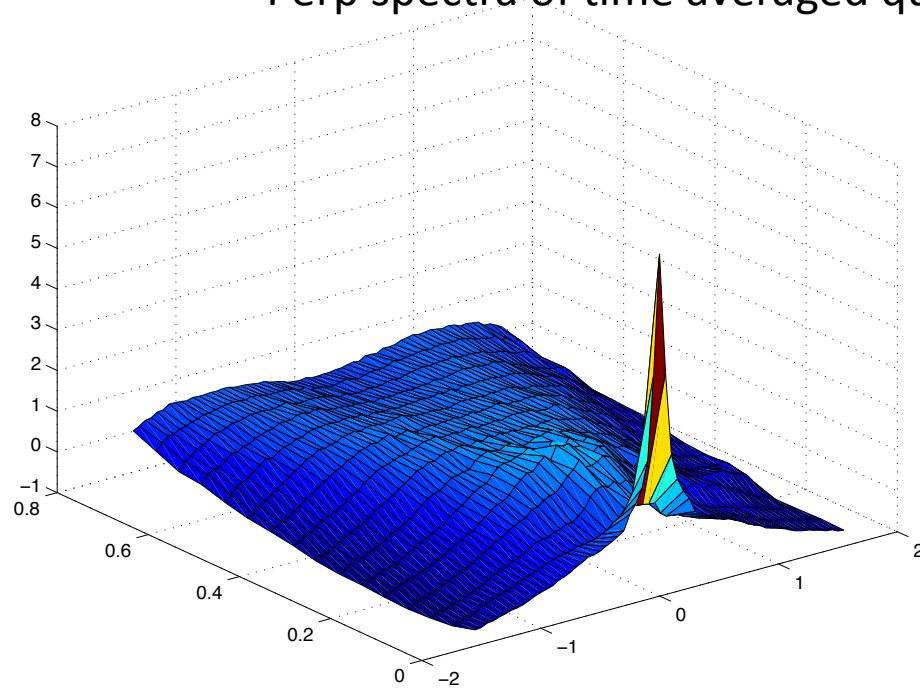
Hyperdiffusions:  
Free energy sinks

$$\mathcal{H}_{v_{\parallel}} = \Omega. h_{v_{\parallel}} \partial_{v_{\parallel}}^4 f_{kj}$$

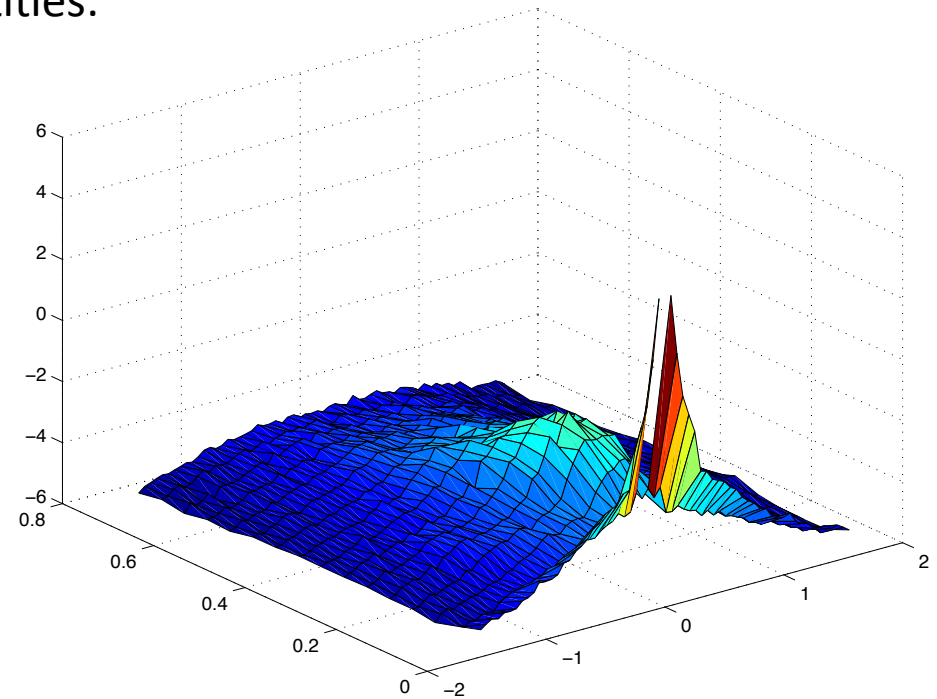


## Free energy balance – terms: lhs

Perp spectra of time averaged quantities:

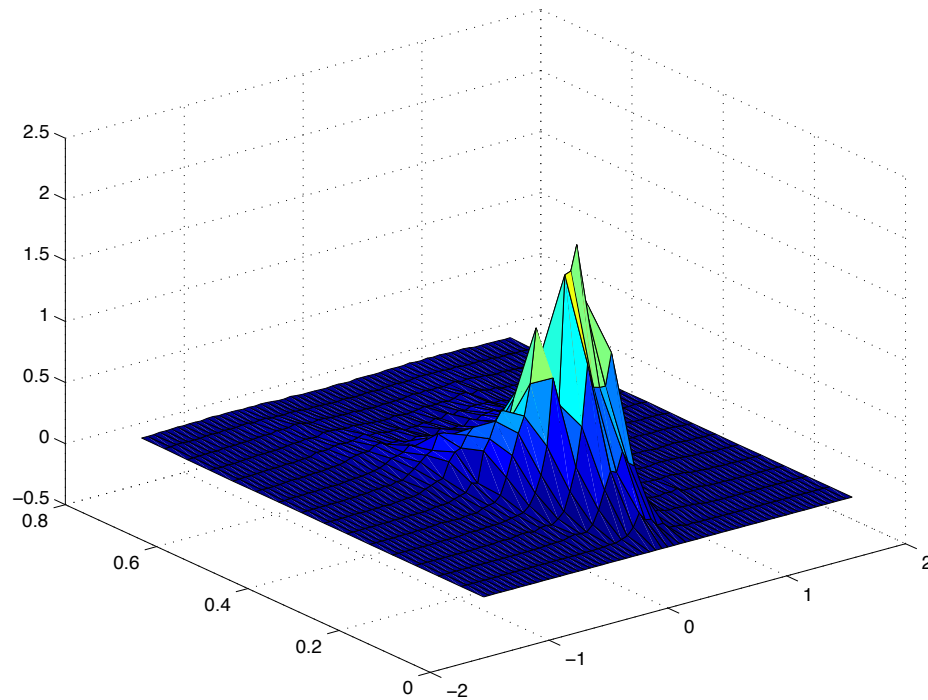


Entropy

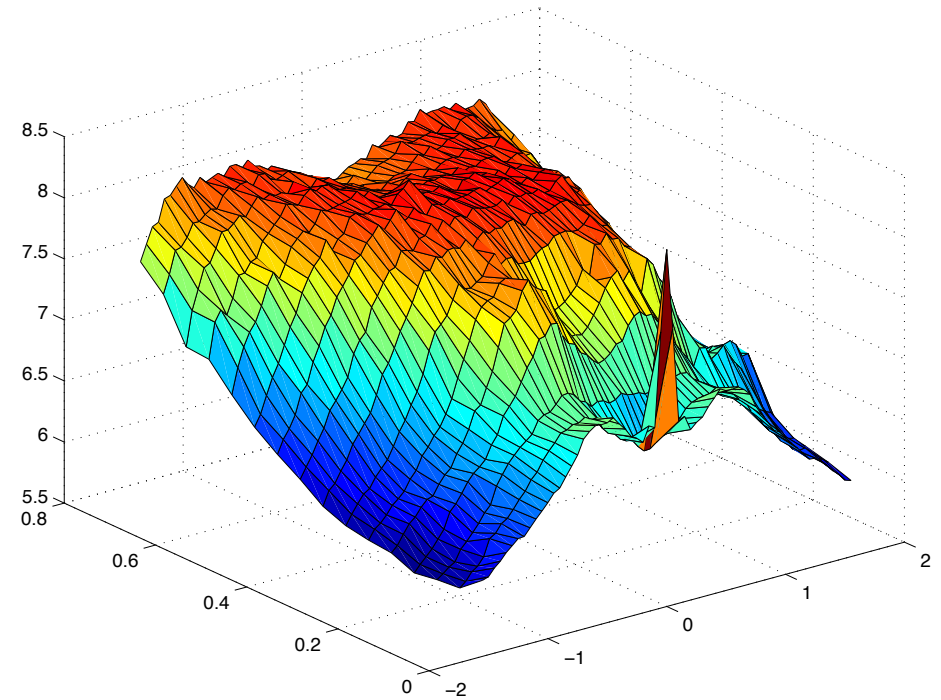


electrostatic energy

*Free energy balance – terms: rhs*



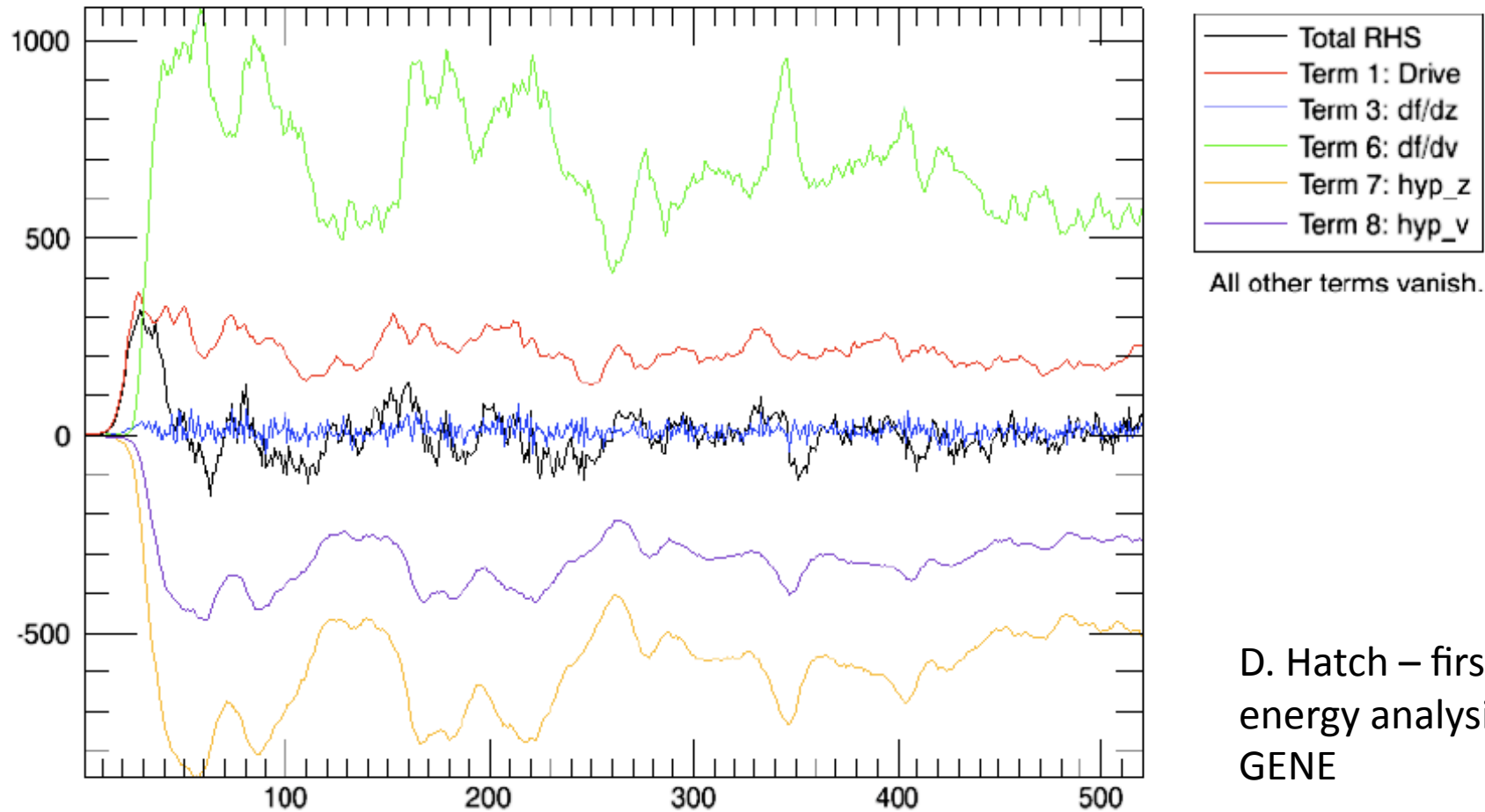
Fluxes drive (eq. gradients)



velocity hyperdiffusion (log scale)

**Free energy balance – conservation in time**

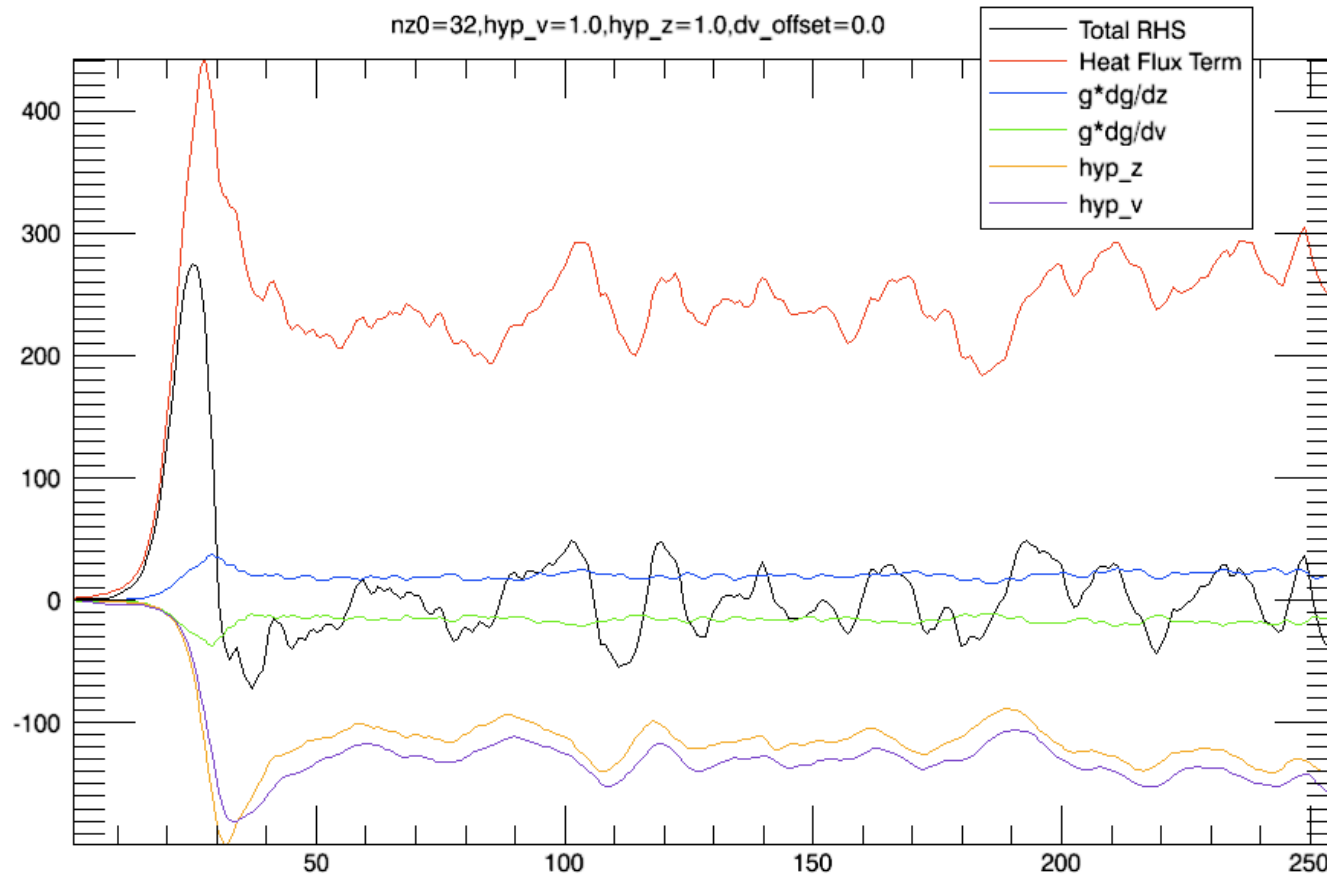
Formally, the parallel derivatives terms should cancel under v-z integration – Not always verified numerically:



D. Hatch – first free energy analysis with GENE

## Free energy balance – conservation in time

modified velocity boundaries (based on  $H_0$  trajectories)



Source: G

Parallel  
derivatives:  
Very closed to 0

Sinks: hyp terms

## *Free energy balance - nonlinearity*

Nonlinear term has no action in the total entropy balance (thanks to PB)

Is responsible of the mode to mode transfer:

$$\mathcal{N}[g_{kj}] = \sum_{k'_\perp} (k'_x k_y - k_x k'_y) \chi_j(k'_\perp) g_j(k_\perp - k'_\perp)$$

## Free energy balance - nonlinearity

The free energy balance depends on resolution

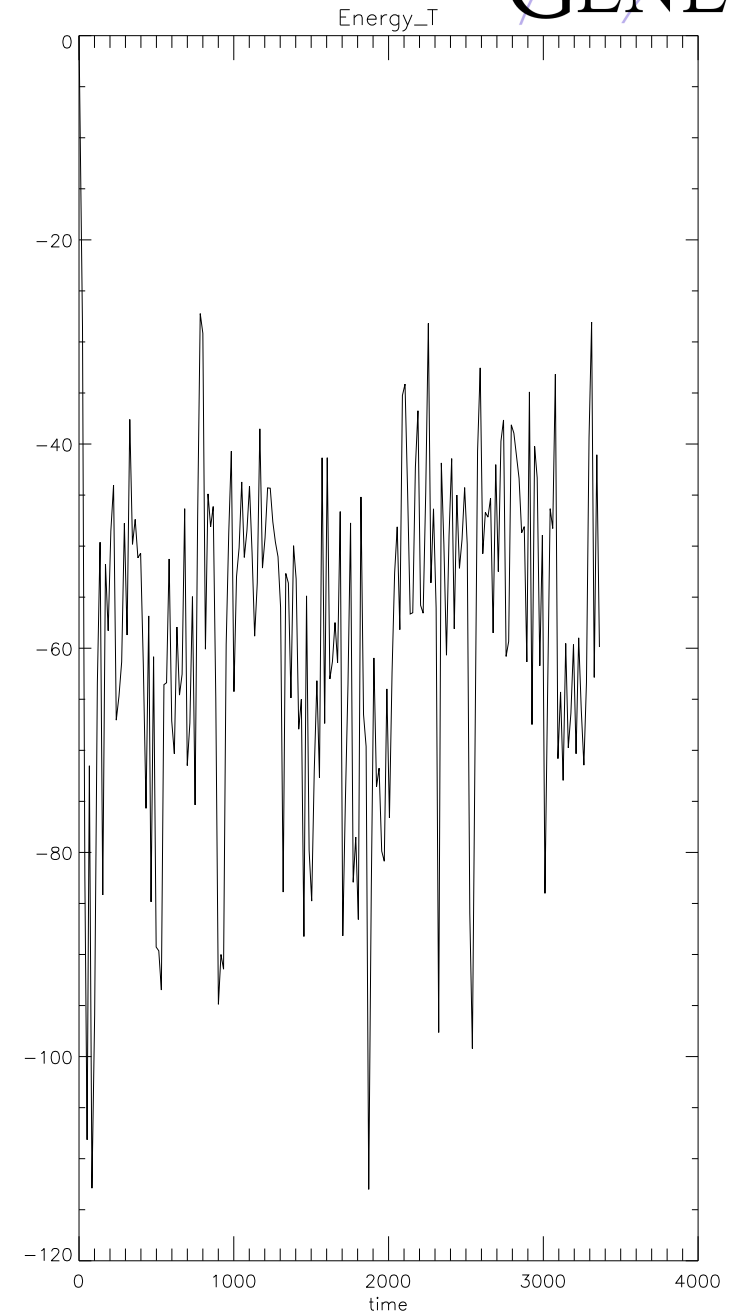
$$\partial_t \left( \overline{\mathcal{F}} + \overline{\mathcal{W}\phi} \right) =$$

$$\overline{\mathcal{G}_0} + \overline{\mathcal{G}} + \overline{\mathcal{H}_z} + \overline{\mathcal{H}_{v_{\parallel}}} + \overline{\Omega \cdot \mathcal{T}[\delta g_{kj}, \delta g_{kj}]}$$

The filtering introduces the sub grid term T  
must act as a dissipation of the resolved scales:

$$\overline{\Omega \cdot \mathcal{T}[\delta g_{kj}, \delta g_{kj}]} < 0$$

Verified numerically:



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In collisionless regime, dissipation is ensured by hyper-diffusion terms.

Such terms depends on the numerics, in GENE:

$$H_{\{z, v_{\parallel}\}} = -i^n \varepsilon_c \left( \frac{\Delta\{z, v_{\parallel}\}}{2} \right)^n \partial_{\{z, v_{\parallel}\}}^n \delta f$$

Practically, prefactor is a fixed parameter in most of cases

NB: a detailed study of these terms can be found in M. Pueschel Thesis



Analyze correlation between hyp's and sub grids:

$$C = \frac{\langle \mathcal{M} | \mathcal{T} \rangle}{\sqrt{\langle \mathcal{M}^2 \rangle \langle \mathcal{T}^2 \rangle}}$$

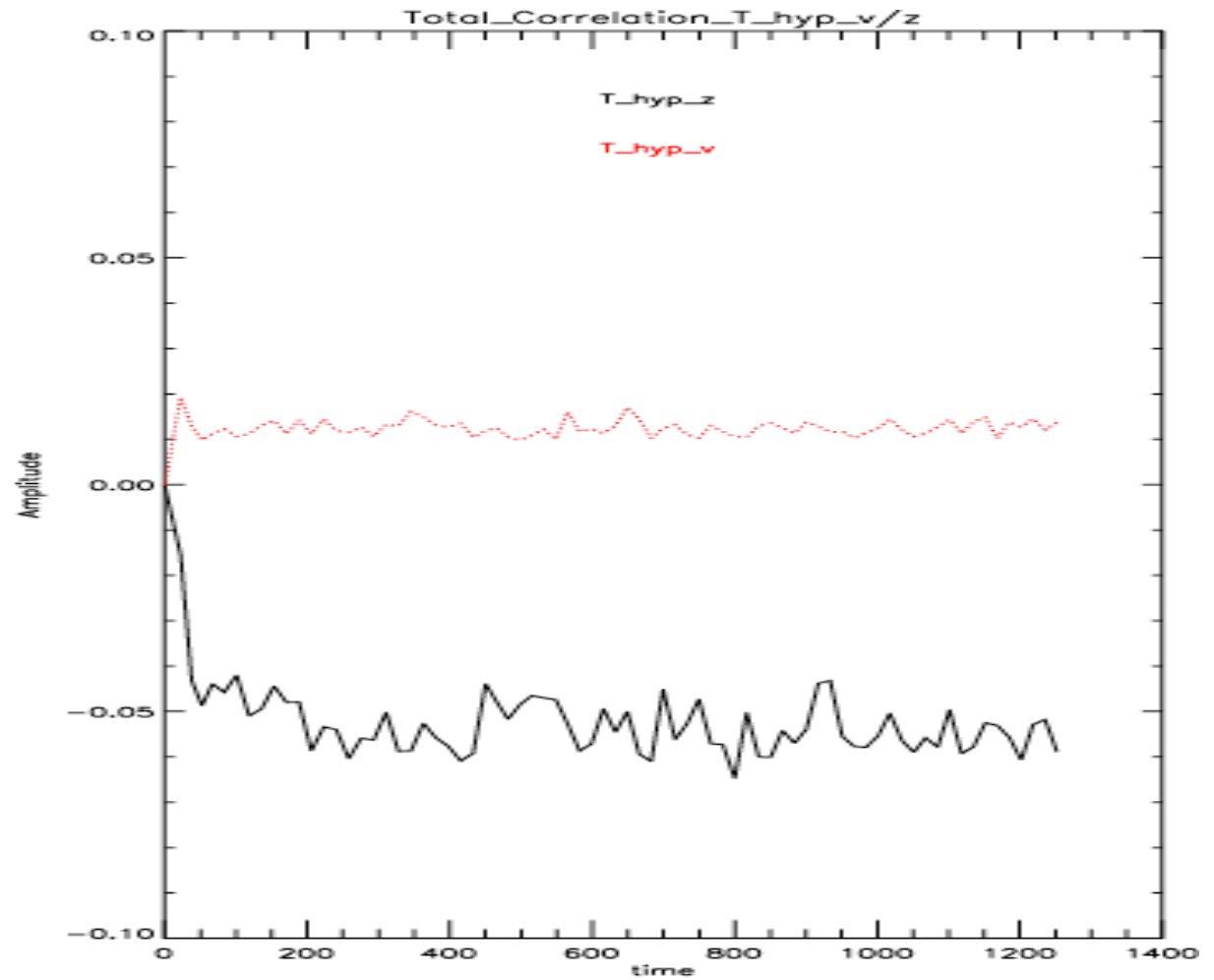
With hyp's as model:

$$\mathcal{M} = h_z \partial_z^4 \overline{\delta f} + h_v \partial_v^4 \overline{\delta f}$$

$$\mathcal{T} = \overline{\mathcal{N}[\delta g, \delta g]} - \mathcal{N}[\overline{\delta g}, \overline{\delta g}]$$

*Hyper-diffusion as model*

Correlation betw T and hyp's during time

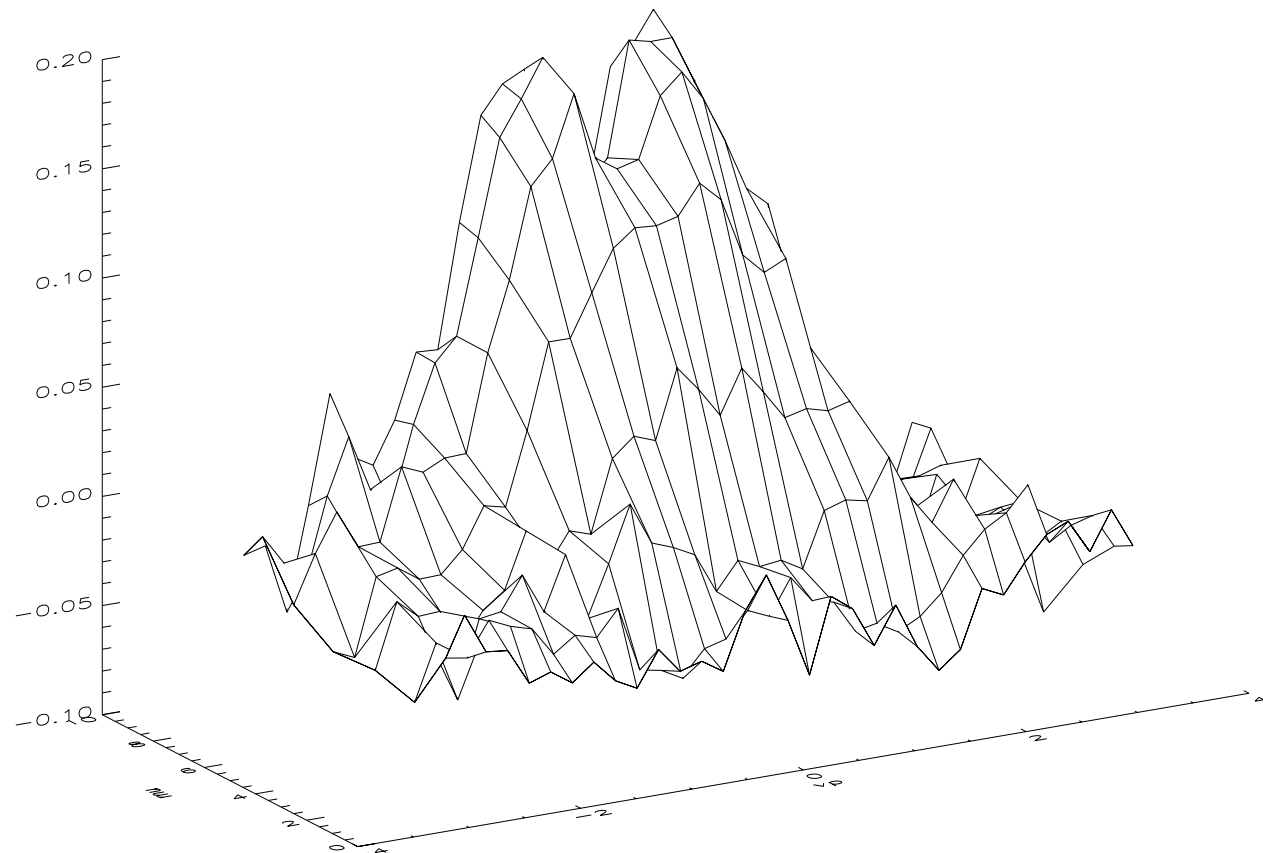


Reach stable but low level

## *Hyper-diffusion as model*

### Velocity plane correlations

Good correlations at mid domains in velocity plane



## *Hyper-diffusion as model*

Free energy: velocity hyperdiffusion act on  $f/F_0$

$$H_{v_{\parallel}} = -c_{v_{\parallel}} \partial_{v_{\parallel}}^4 \frac{\delta f}{F_0}$$

Action: damps free energy till perturbed  $\delta f$  reaches a constant ratio of equilibrium

$$\partial_t \left\langle \frac{|\delta f|^2}{F_0} \right\rangle \propto -2c_{v_{\parallel}} \left\langle \left| \partial_{v_{\parallel}}^2 \frac{\delta f}{F_0} \right|^2 \right\rangle$$

$$\partial_t \langle \delta f \rangle \propto -c_{v_{\parallel}} \left\langle \partial_{v_{\parallel}}^4 \frac{\delta f}{F_0} \right\rangle$$

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### Dynamic procedure

consider a simulation with model:  $\mathcal{T} \approx c m(\overline{\delta g}, \overline{\Delta})$

$$\partial_t \overline{\delta g}_{\Delta} = \mathcal{L}_{\Delta}[\overline{\delta g}_{\Delta}] + \mathcal{N}_{\Delta}[\overline{\delta g}_{\Delta}, \overline{\delta g}_{\Delta}] + c m_{\Delta}(\overline{\delta g}_{\Delta}, \overline{\Delta}) \quad (1)$$

introduce an intermediate scale, keep same resolution, complete with zeroes:

$$\partial_t \widehat{\delta g}_{\Delta} = \mathcal{L}_{\Delta}[\widehat{\delta g}_{\Delta}] + \mathcal{N}_{\Delta}[\widehat{\delta g}_{\Delta}, \widehat{\delta g}_{\Delta}] + c m_{\Delta}(\widehat{\delta g}_{\Delta}, \widehat{\Delta})$$

filter eq(1) at intermediate scale:

$$\widehat{X} = \widehat{X} \quad \partial_t \widehat{\delta g}_{\Delta} = \mathcal{L}_{\Delta}[\widehat{\delta g}_{\Delta}] + \mathcal{N}_{\Delta}[\widehat{\delta g}_{\Delta}, \widehat{\delta g}_{\Delta}] + c m_{\Delta}(\widehat{\delta g}_{\Delta}, \widehat{\Delta})$$

minimization leads to the value of c:

$$c = \frac{\langle \mathcal{M} \mathcal{T}_{\Delta}^{\widehat{\Delta}} \rangle}{\langle \mathcal{M} \mathcal{M} \rangle} \quad \mathcal{M} = m_{\Delta}(\widehat{\delta g}, \widehat{\Delta}) - m_{\Delta}(\overline{\delta g}, \overline{\Delta})$$

$$\mathcal{T}_{\Delta}^{\widehat{\Delta}} = \mathcal{N}_{\Delta}[\widehat{\delta g}_{\Delta}, \widehat{\delta g}_{\Delta}] - \mathcal{N}_{\Delta}[\overline{\delta g}_{\Delta}, \overline{\delta g}_{\Delta}]$$

*Dynamic procedure*

